



## Personal information

Name / Surname	<b>Zanlungo Francesco</b>
Address	Viale Bacchiglione 21, 20139, Milano, Italy; Salita Sant'Antonio 19, 90133, Palermo Italy
Telephone	(+39) 4406673
Personal Email	zanlungo@atr.jp, francesco.zanlungo@gmail.com, francesco.zanlungo@unipa.it
Home page	<a href="https://zanlungo.github.io/">https://zanlungo.github.io/</a>
Nationality	Italian, Holder of Japanese permanent residence permit
Date of birth	10/03/1976
Gender	Male

## Research keywords

Complex Systems Modelling, Crowd Behaviour, Simulations, Robotics

## Professional experience

October 2024- Present	RTDB, (Tenure track Assistant Professor) Palermo University, Palermo, Italy
October 2022 -	Contract consultant Standard AI, San Francisco, US
October 2021 -February 2024	Contract lecturer Okayama University, Okayama, Japan
April 2021 - September 2024	Lecturer International Professional University of Technology, Osaka, Japan Permanent position
April 2020 - June 2024	Part time researcher Okayama University, Okayama, Japan
April 2017-March 2020 June 2020-Present	Collaborative researcher Intelligent Robotics and Communication Laboratories, ATR, Kyoto, Japan

November 2016-March 2017	Researcher Intelligent Robotics and Communication Laboratories, ATR, Kyoto, Japan
2015-2016	Lecturer in Applied Mathematics Kingston University, London, UK Faculty of Science, Engineering and Computing, School of Computer Science and Mathematics Tenured position
2009-2015	Researcher Intelligent Robotics and Communication Laboratories, ATR, Kyoto, Japan
November 2008 and September 2009	Visiting researcher  CPT (Theoretical Physics Center), Marseilles, France Collaboration with Prof. Sandro Vaienti
2008	Instructor Milan Polytechnic University Teaching Introductory course of Mathematics ("College Algebra")
2007-2009	Post-doctoral researcher University of Bologna Analysis of the effect of random noise and numerical round-off on discrete maps
June-September 2005	Visiting researcher Artificial Life Laboratory at Nagoya University Collaboration with Prof. Takaya Arita
<b>Journal editing</b>	
From August 2018	Area Editor Simulation Modelling Practice and Theory, Elsevier
<b>Professional experience outside research</b>	
2017-2024	Instructor of conversational Italian language Japan-Italy Society of Okayama
<b>Education and training</b>	
2004-2007	Ph.D. course
Major	Theoretical Physics
Institution	Graduate school of Physics, University of Bologna, Italy
Graduation Thesis	Microscopic Dynamics of Artificial Life Systems, supervised by Prof. Giorgio Turchetti
2003	Japanese language education
Institution	Yamasa Language school, Okazaki-shi, Aichi-ken, Japan
2002	Italian Laurea in Physics <i>(The Italian "Laurea" is legally equivalent to a Master degree. To obtain the degree, the candidate was supposed to work on a one year Graduation Thesis project requiring original research.)</i>

Major  
Institution  
Graduation Thesis

Theoretical Physics  
University of Milan, Italy  
Studio numerico della cascata ultravioletta nel modello  $\phi^4$  classico (in Italian), supervised by Prof. Claudio Destri

## Languages

Mother tongue

Self-assessment  
European level<sup>(\*)</sup>

**English**

**Japanese(\*\*)**

**Spanish**

**Portuguese**

**French**

**Turkish**

**Mandarin Chinese**

Home page

Driving licence(s)

Personal interests

## Italian

Understanding				Speaking				Writing	
Listening		Reading		Spoken interaction		Spoken production			
C2	Proficient user	C2	Proficient user	C2	Proficient user	C2	Proficient user	C2	Proficient user
C1	Proficient user	C1	Proficient user	C1	Proficient user	C1	Proficient user	C1	Proficient user
C2	Proficient user	C2	Proficient user	C1	Proficient user	C1	Proficient user	C1	Proficient user
C1	Proficient user	C1	Proficient user	B2	Independent user	B2	Independent user	B1	Independent user
B2	Independent user	C1	Proficient user	B1	Independent user	B1	Independent user	A2	Basic user
A2	Basic user	A2	Basic user	A2	Basic user	A1	Basic user	A2	Basic user
A1	Basic user	A2	Basic user	A1	Basic user	A1	Basic user	A2	Basic user

<sup>(\*)</sup>Common European Framework of Reference (CEF) level

<sup>(\*\*)</sup>Holder of first (highest) level of Japanese proficiency, approved in 2008

<https://zanlungo.github.io/>

B (cars)

Foreign languages, swimming, running, cycling, basketball, traveling, music, digital photography, books in general, my family.

## Publications

### Journal papers

- 1 A. Gregorj, Z. Yücel, F. Zanlungo, T. Kanda  
*Ecological data reveal imbalances in human–human collision avoidance due to dyads’ social interaction*  
Transportation Research Part F: Traffic Psychology and Behaviour 109 (2025): 1313-1333
- 2 A. Gregorj, Z. Yücel, F. Zanlungo, C. Feliciani, T. Kanda  
*Social aspects of collision avoidance: a detailed analysis of two-person groups and individual pedestrians*  
Scientific reports 13.1 (2023): 5756.
- 3 F. Zanlungo, C. Feliciani, Z. Yücel, X. Jia, K. Nishinari, T. Kanda  
*A pure number to assess “congestion” in pedestrian crowds*  
Transportation Research Part C: Emerging Technologies 148, 104041, 2023  
<https://doi.org/10.1016/j.trc.2023.104041>
- 4 F. Zanlungo, C. Feliciani, Z. Yücel, K. Nishinari, T. Kanda  
*Macroscopic and microscopic dynamics of a pedestrian cross-flow: Part II, modelling*  
Safety Science 158, 105969, 2023  
<https://doi.org/10.1016/j.ssci.2022.105969>
- 5 F. Zanlungo, C. Feliciani, Z. Yücel, K. Nishinari, T. Kanda  
*Macroscopic and microscopic dynamics of a pedestrian cross-flow: Part I, experimental analysis*  
Safety Science 158, 105953, 2023  
<https://doi.org/10.1016/j.ssci.2022.105953>
- 6 F. Zanlungo, Z. Yücel, T. Kanda  
*Intrinsic group behaviour II: On the dependence of triad spatial dynamics on social and personal features; and on the effect of social interaction on small group dynamics*  
PloS One, Vol 14, No 12, pp e0225704, 2019  
doi: 10.1371/journal.pone.0225704
- 7 Z. Yücel, F. Zanlungo, C. Feliciani, Claudio, A. Gregorj, T. Kanda  
*Identification of social relation within pedestrian dyads*  
PloS One, Vol 14, No 10, pp e0223656, 2019  
doi: 10.1371/journal.pone.0223656
- 8 39 authors including F. Zanlungo  
*A Glossary for Research on Human Crowd Dynamics*  
Collective Dynamics, Vol. 4, pp. 1-13, 2019  
doi: 10.17815/CD.2019.19
- 9 Z. Yücel, F. Zanlungo and M. Shiomi  
*Modeling the impact of interaction on pedestrian group motion*  
Advanced Robotics, Vol. 32, No 3, pp. 137-147, 2018  
doi: 10.1080/01691864.2017.1421481
- 10 F. Zanlungo, Z. Yücel, D. Bršćić, T. Kanda, N. Hagita  
*Intrinsic group behaviour: dependence of pedestrian dyad dynamics on principal social and personal features*  
Plos One 0187253, 2017

doi: 10.1371/journal.pone.0187253

- 11 F. Zanlungo, T. Kanda  
*A mesoscopic model for the effect of density on pedestrian group dynamics*  
Europhysics Letters, Vol. 111, No 3, pp. 38007, 2015  
doi: 10.1209/0295-5075/111/38007
- 12 F. Zanlungo, D. Brščić, T. Kanda  
*Spatial-size scaling of pedestrian groups under growing density conditions*  
Physical Review E Vol. 91 No 6, pp. 062810, 2015  
doi: 10.1103/PhysRevE.91.062810
- 13 M. Shiomi, F. Zanlungo, K. Hayashi , T. Kanda  
*Towards a Socially Acceptable Collision Avoidance for a Mobile Robot Navigating Among Pedestrians Using a Pedestrian Model*  
International Journal of Social Robotics, Vol. 6, No 3, pp 443-455, 2014  
doi: 10.1007/s12369-014-0238-y
- 14 F. Zanlungo, T. Ikeda, T. Kanda  
*Potential for the dynamics of pedestrians in a socially interacting group*  
Physical Review E Vol. 89, No 1, pp. 012811, 2014  
doi: 10.1103/PhysRevE.89.012811
- 15 Z. Yücel, F. Zanlungo, T. Ikeda, T. Miyashita, N. Hagita  
*Deciphering the crowd: Modeling and identification of pedestrian group motion*  
Sensors, Vol. 13, No. 1, pp. 875-897, 2013  
doi: 10.3390/s130100875
- 16 F. Zanlungo, T. Ikeda, T. Kanda  
*A microscopic social norm model to obtain realistic macroscopic velocity and density pedestrian distributions*  
PLoS ONE Vol. 7, No 12, pp. e50720, 2012  
doi: 10.1371/journal.pone.0050720
- 17 F. Zanlungo, T. Ikeda, T. Kanda  
*Social force model with explicit collision prediction*  
Europhysics Letters, Vol. 93, No. 6, pp. 68005, 2011  
doi: 10.1209/0295-5075/93/68005
- 18 G. Turchetti, S. Vaienti and F. Zanlungo  
*Asymptotic distribution of global errors in the numerical computations of dynamical systems*  
Physica A, Vol. 389, No 21, pp. 4994-5006, 2010  
doi: 10.1016/j.physa.2010.06.060
- 19 G. Turchetti, S. Vaienti and F. Zanlungo  
*Relaxation to the asymptotic distribution of global errors due to round off*  
Europhysics Letters, Vol. 89, No 4, pp. 40006, 2010  
doi: 10.1209/0295-5075/89/40006
- 20 P. Marie, G. Turchetti, S. Vaienti and F. Zanlungo  
*Error distribution in randomly perturbed orbits*  
Chaos: An Interdisciplinary Journal of Nonlinear Science, Vol. 19, No 4, pp. 043118, 2009  
doi: 10.1063/1.3267510

- 21 F. Zanlungo, T. Arita, S. Rambaldi  
*Emergence of a traffic flow convention in a multiagent model*  
Advances in Complex Systems. Vol. 11, No 5, pp. 789-802, 2008  
doi: 10.1142/S0219525908001921
- 22 G. Turchetti, F. Zanlungo, B. Giorgini  
*Dynamics and thermodynamics of a gas of automata*  
Europhysics Letters, Vol. 78, No 5, pp. 58003, 2007  
doi: 10.1209/0295-5075/78/58003
- 23 F. Zanlungo  
*A collision avoiding mechanism based on a theory of mind*  
Advances in Complex Systems. Vol. 10 suppl. No. 2, pp. 363-371, 2007  
doi: 10.1142/S0219525907001410

### Book chapters

- 24 S. Tsujimoto, T. Kato, R. Kojima, K. Maeda, F. Zanlungo  
*Analysis of Autonomous Many-Body Particle Models from Geometric Perspective and Its Applications*  
Advanced Mathematical Science for Mobility Society, Springer Nature Singapore, 2024
- 25 F. Zanlungo, G. Turchetti, S. Rambaldi  
*An Automata Based Microscopic Model Inspired by Clonal Expansion*  
Mathematical Modeling of Biological Systems, Volume II. A. Deutsch et al. (eds.), Birkhäuser, Boston, pp. 133-144, 2008  
doi: 10.1007/978-0-8176-4556-4\_12

### Conference papers

- 26 A. Gregorj, Z. Yücel, F. Zanlungo, T. Kanda  
*Asymmetries in group-individual collision avoidance due to social factors*  
Collective Dynamics, 9, 1-9
- 27 F. Zanlungo, Z. Yücel, C. Feliciani, K. Nishinari, T. Kanda  
*Congestion Number Analysis of Cross-Flow Dynamics: Experimental Data and Simulations*  
Collective Dynamics, 9, 1-8
- 28 F. Zanlungo, C. Feliciani, H. Murakami, Z. Yücel, X. Jia, K. Nishinari, T. Kanda  
*Density dependence of stripe formation in a cross-flow*  
International Conference on Traffic and Granular Flow (TGF 2022)  
15-17 October 2022, Delhi, India
- 29 A. Gregorj, Z. Yücel, F. Zanlungo, T. Kanda  
*On the influence of group social interaction on intrusive behaviors*  
International Conference on Traffic and Granular Flow (TGF 2022)  
15-17 October 2022, Delhi, India
- 30 F. Zanlungo, C. Feliciani, Z. Yücel, K. Nishinari, T. Kanda  
*Crowd congestion number*  
Pedestrian and Evacuation Dynamics, PED 2021  
Dec 2021, Melbourne, Australia
- 31 A. Gregorj, Z. Yücel, F. Zanlungo, C. Feliciani, T. Kanda  
*On the influence of group social relation on the dynamics of pedestrians outside the group*  
Pedestrian and Evacuation Dynamics, PED 2021  
Dec 2021, Melbourne, Australia

- 32 E. Repiso, F. Zanlungo, T. Kanda, A. Garrell, A. Sanfeliu  
*People's V-Formation and Side-by-Side Model Adapted to Accompany Groups of People by Social Robots*  
International Conference on Intelligent Robots and Systems 2019, pp. 2082-2088  
Nov 4-8 2019, Macau, China  
doi: 10.1109/IROS40897.2019.8968601
- 33 Z. Yücel, F. Zanlungo, T. Kanda  
*Gender profiling of pedestrian dyads*  
Traffic and Granular Flow Conference 2019, pp. 299-305  
July 2-5 2019, Pamplona, Spain  
doi: 10.1007/978-3-030-55973-1\_37
- 34 F. Zanlungo, L. Crociani, Z. Yücel, T. Kanda  
*The effect of social groups on the dynamics of bi-directional pedestrian flow: a numerical study*  
Traffic and Granular Flow Conference 2019, pp. 307-313  
July 2-5 2019, Pamplona, Spain  
doi: 10.1007/978-3-030-55973-1\_38
- 35 C. Feliciani, F. Zanlungo, K. Nishinari, T. Kanda  
*Thermodynamics of a gas of pedestrians: Theory and experiment*  
Pedestrian and Evacuation Conference 2018  
Collective Dynamics, Vol 5, pp. 440-447, 2020  
Aug 21-24 2018, Lund, Sweden  
doi: 10.17815/CD.2020.97
- 36 Z. Yücel, F. Zanlungo, C. Feliciani, T. Kanda  
*Estimating social relation from trajectories*  
Pedestrian and Evacuation Conference 2018  
Collective Dynamics, Vol 5, pp. 222-229, 2020  
Aug 21-24 2018, Lund, Sweden  
doi: 10.17815/CD.2020.54
- 37 F. Zanlungo, Z. Yücel, T. Kanda  
*Social group behaviour of triads. Dependence on purpose and gender*  
Pedestrian and Evacuation Conference 2018  
Collective Dynamics, Vol 5, pp. 118-125, 2020  
Aug 21-24 2018, Lund, Sweden  
doi: 10.17815/CD.2020.90
- 38 F. Zanlungo, Z. Yücel, F. Ferreri, J. Even, L.Y. Morales Saiki, T. Kanda  
*Pedestrian models for robot motion*  
Pedestrian and Evacuation Conference 2018  
Collective Dynamics, Vol 5, pp. 525-527, 2020  
Aug 21-24 2018, Lund, Sweden  
doi: 10.17815/CD.2020.90
- 39 Z. Yücel, F. Zanlungo and M. Shiomi  
*Walk the talk: Gestures in mobile interaction*  
International Conference on Social Robotics 2017, pp. 220-230  
Nov 22-24 2017, Tsukuba, Japan  
doi: 10.1007/978-3-319-70022-9\_22
- 40 F. Zanlungo, Z. Yücel, F. Ferreri, J. Even, L.Y. Morales Saiki, T. Kanda

- Social group motion in robots*  
International Conference on Social Robotics 2017, pp. 474-484, Tsukuba, Japan  
doi: 10.1007/978-3-319-70022-9\_47
- 41 D. Brščić, F. Zanlungo, T. Kanda  
*Modelling of Pedestrian groups and application to group recognition*  
40th International Convention on Information Information and Communication Technology, Electronics and Microelectronics (MIPRO), 2017, pp. 564-569, Opatija, Croatia  
doi: 10.23919/MIPRO.2017.7973489
- 42 K. Kamei, F. Zanlungo, T. Kanda, Y. Horikawa, T. Miyashita, N. Hagita  
*Cloud networked robotics for social robotic services extending robotic functional service standards to support autonomous mobility system in social environments*  
International Conference on Ubiquitous Robots and Ambient Intelligence (URAI), 2017, pp. 897-902, Jeju, South Korea  
doi: 10.1109/URAI.2017.7992862
- 43 F. Zanlungo, Z. Yücel, T. Kanda  
*The effect of social roles on group behaviour*  
Pedestrian and Evacuation Conference 2016, pp. 243-249, Hefei, China  
doi: 10.17815/CD.2016.11
- 44 F. Zanlungo, D. Brščić, T. Kanda  
*Pedestrian group behaviour analysis under different density conditions*  
Pedestrian and Evacuation Conference 2014, Delft, Netherlands  
Transportation Research Procedia Vol. 2, 149-158, 2014  
doi: 10.1016/j.trpro.2014.09.020
- 45 D. Brščić, F. Zanlungo, T. Kanda  
*Density and velocity patterns during one year of pedestrian tracking*  
Pedestrian and Evacuation Conference 2014, Delft, Netherlands  
Transportation Research Procedia 2, 77-86, 2014  
doi: 10.1016/j.trpro.2014.09.011
- 46 F. Zanlungo, T. Kanda  
*Do walking pedestrians stably interact inside a large group? Analysis of group and sub-group spatial structure*  
The annual meeting of cognitive science society (CogSci) 2013, Vol. 35, No. 35, pp. 3847-3852, Berlin, Germany
- 47 T. Ikeda, Y. Chigodo, D. Rea, F. Zanlungo, M. Shiomi, T. Kanda  
*Modeling and Prediction of Pedestrian Behavior based on the Sub-goal Concept*  
Robotics: Science and Systems (RSS) 2013, pp. 137-144, Sidney, Australia (acceptance rate 33%)  
doi: 10.15607/RSS.2012.VIII.018
- 48 F. Zanlungo, Y. Chigodo, T. Ikeda, T. Kanda  
*Experimental study and modelling of pedestrian space occupation and motion pattern in a real world environment*  
Pedestrian and Evacuation Dynamics 2012, Zurich, Switzerland  
Weidmann et al. (eds.), pp. 289-304, Springer, (published as a book in 2014)  
doi: 10.1007/978-3-319-02447-9\_24
- 49 M. Shiomi, F. Zanlungo, K. Hayashi, T. Kanda

- A Framework with a Pedestrian Simulator for Deploying Robots into a Real Environment*  
International Conference on Simulation, Modeling, and Programming for Autonomous Robots 2012 (SIMPAN), pp. 185-196, (acceptance rate 35%)  
doi: 10.1007/978-3-642-34327-8\_19
- 50 Z. Yücel, F. Zanlungo, T. Ikeda, T. Miyashita, N. Hagita  
*Modeling Indicators of Coherent Motion*  
International Conference on Intelligent Robots and Systems (IROS) 2012, pp 2134–2140, Algarve, Portugal (acceptance rate 39%) 2012  
doi: 10.1109/IROS.2012.6385744
- 51 M. D. Cooney, F. Zanlungo, S. Nishio, H. Ishiguro  
*Designing a Flying Humanoid Robot (FHR): Effects of Flight on Interactive Communication*  
International Symposium on Robot and Human Interactive Communication (IEEE RO-MAN) 2012, pp. 364-371, 2012, Paris, France  
doi: 10.1109/ROMAN.2012.6343780
- 52 A. Bazzani, B. Giorgini, F. Zanlungo and S. Rambaldi  
*Cognitive Dynamics in an automata gas*  
Artificial Life and Evolutionary Computation, pp. 3-19, Wivace 2008, Venice, Italy  
doi: 10.1142/9789814287456\_0001
- 53 F. Zanlungo  
*Evolution of high level recursive thinking in a collision avoiding agent model*  
Artificial Life and Evolutionary Computation, pp. 155-164, Wivace 2008, Venice, Italy  
doi: 10.1142/9789814287456\_0014
- 54 F. Zanlungo, A. Bazzani, B. Giorgini, S. Rambaldi, G. Servizi and G. Turchetti  
*An evolutionary crowd dynamics model*  
European Conference on Complex Systems 2007, Dresden Germany
- 55 F. Zanlungo, T. Arita  
*Evolutionary Simulation of an Agent Based Mobility System Using Indirect Communication*  
International Symposium of Artificial Life and Robotics (A-Life) 2006, pp. 319-322, Oita, Japan