Bahman Gharesifard

Curriculum vitae: November, 2023

Professor

UCLA Samueli Electrical and Computer Engineering

University of California, Los Angeles

Address:

58-115 Engineering IV Building 420 Westwood Plaza (Box 951594) Los Angeles, CA 90095-1594

Email: gharesifard@ucla.edu https://gharesifard.github.io

July 2021-

July 2023-

July 2023 -

July 2019 - June 2021

July 2013 - July 2019

Summer 2016

October 2019 - December 2021

POSITIONS

Professor, University of California, Los Angeles

 $Area\ Director\ for\ Signals\ and\ Systems$

UCLA Samueli School of Engineering

Department of Electrical and Computer Engineering

Professor of Mathematics, Queen's University

Department of Mathematics and Statistics

Associate Professor, Queen's University

Department of Mathematics and Statistics

Alexander von Humboldt Fellow, University of Stuttgart

Institute for Systems Theory and Automatic Control

Assistant Professor, Queen's University

Department of Mathematics and Statistics

Ontario/Baden-Württemberg Visiting Faculty, University of Stuttgart

Institute for Systems Theory and Automatic Control

Postdoctoral Research Associate, University of Illinois, Urbana-Champaign March 2012 – July 2013 Coordinated Science Laboratory

Department of Electrical and Computer Engineering

Postdoctoral Research Associate, University of California San Diego September 2009 – March 2012

Jacobs School of Engineering

Department of Mechanical and Aerospace Engineering

EDUCATION

Ph.D., Mathematics

Queen's University, Kingston, ON, Canada

October 2009

B.Sc. and M.Sc., Mechanical Engineering (Dynamics and Control)

Shiraz University, Shiraz, Iran

May 2005

RESEARCH INTERESTS

Decision Theory: systems and control; stability of discrete-time/continuous-time dynamical systems; autonomy; networked control systems; cyber-physical systems; robotic networks; sensor networks; discontinuous dynamical systems; nonlinear and geometric control; controllability of partial differential equations; economic dispatch of energy in networked power systems; identification and adaptation

Machine Learning and Optimization Theory: mathematical theory of neural networks; reinforcement learning; decentralized optimization; submodular optimization; online learning; continuous-time optimization algorithms; optimal transportation theory

Social Networks: opinion dynamics; diffusion models; reinforcement schemes; random graphs

Game Theory and Economics: game theory and strategic interactions; market design in distributed settings; learning in games

Stochastic Processes and Probability Theory: stochastic reinforcement processes, stochastic differential equations and control; rough path theory

Global Analysis: applied differential geometry; exterior differential systems; Lie theory, Riemannian geometry; geometric theory of partial differential equations

AWARDS AND HONORS

Canadian Society of Information Theory Best Paper Award	2022
Best conference paper that has been accepted by either the Biennial Symposium on Communications (BSC) or the Ca	ınadian
Workshop on Information Theory (CWIT)	
SIAG/CST Best SICON Paper Prize 2021	2021
Awarded to the author(s) of the two most outstanding papers, as determined by the prize committee, published in the SIAM	
Journal on Control and Optimization (SICON) in the three calendar years before the award year	
Booz Allen Hamilton Distinguished Colloquium Lecture, University of Maryland	2020
Alexander von Humboldt Fellowship for experienced researchers	2019
The 2019 CAIMS-PIMS Early Career Award	2019
Jointly awarded by the Canadian Applied & Industrial Math Society and the Pacific Institute for the Mathematical Sciences	
NSERC Discovery Accelerator Supplement	2019
supplemental funding with 125 recipients among over 3000 applicants in Canada	
Finalist for Best Paper Award (as a supervisor), American Control Conference	2017
Class of 2020 Engineering and Applied Science First Year Instructor Teaching Award	2017
Class of 2018 Engineering and Applied Science First Year Instructor Teaching Award	2015
Shortlisted for the Frank Knox Award for Excellence in Teaching	2014

RESEARCH GRANTS

National Science Foundation	
Structural Frameworks for Output Control of Continuum Ensemble Systems (with Xudong C	Chen) 2023
National Science Foundation	
Formally correct deep perception for cyber-physical systems (with Paulo Tabuada)	2022
Fields Centre for Quantitative Analysis and Modeling	
co-PI of one of the six labs	2018-2021
Alexander von Humboldt Fellowship for experienced researchers	2019-2020
Ontario/Baden-Württemberg Exchange Program	May-July 2016
visiting the Institute for Systems Theory and Automatic Control, University of Stuttgart	

NSERC Discovery Grant NSERC Discovery Accelerator Supplement Senate Advisory Research Committee Grant	2014- 2019 2014-2015
ADMINISTRATIVE ACTIVITES	
UCLA Samueli Faculty Executive Committee Chair, Honors Committee, UCLA Samueli Colloquium Chair, UCLA Signals and Systems Graduate Admissions Committee, UCLA Chair, CAIMS-PIMS Early Career Award CAIMS-PIMS Early Career Award Committee Postdoctoral Committee, Queen's University Appointment Core Committee, Queen's University Chair, Advisory Committee on Policy Queen's University Advisory Committee on Policy, Queen's University First Year Engineering Curriculum Review Committee (FYCRC), Queen's University Graduate Attribute Project Planning Committee (GAPPC), Queen's University Appointment Core Committee, Queen's University Interviewing for Academia and Mock Interview Practice, School of Graduate Studies Graduate committee, Queen's University Math & Stats Colloquium Chair, Queen's University Ontario Graduate Scholarship Reviewer, Queen's University Major Undergraduate Admission Award Reviewer, Queen's University Judge, Andrina McCulloch Public Speaking competition, Mathematics and Engineering Committee, Queen's University	$2022-2025 \\ 2023-2024 \\ 2022 \\ 2022- \\ 2021- \\ 2019- \\ 2017-2018 \\ 2015-2016 \\ 2016-2017 \\ 2015-2017 \\ 2014-2015 \\ 2014-2015 \\ 2014-2015 \\ 2014-2015 \\ 2014-2016 \\ 2014-2016 \\ 2014-2015 \\ 2014-2015 \\ 2014-2015 \\ 2014-2015 \\ 2014-2015 \\ 2014-2015 \\ 2014-2015 \\ 2014-2015 \\ 2014-2015 \\ 2014-2015 \\ 2014-2015 \\ 2013-2015, 2018 \\ 2014, 2015 \\ 2013-2019 \\ \\$
REVIEW, EDITORIAL DUTIES, and ORGANIZED SESSIONS AND CON	IFERENCES
Program Chair Annual Canadian Applied and Industrial Mathematics Society to be held in Kingston, ON, Canada,	June 2024
Vice Program Chair Control and Decision Conference TBA	December 2026
International Program Committee SIAM Conference on Control and Its Applications to be held in Philadelphia, US	July 2023
IEEE CDC 2023 Best Student Paper Award Committee Control and Decision Conference, Singapore	2023

 $Associate\ Editor:$

IEEE Transactions on Control of Network Systems

2021-

Program Committee Member: Learning for Dynamics and Control (L4DC), UC Berkeley, ETH, and Stanford	2020-2022
Associate Editor IEEE Control Systems Letters	2019-2022
Conference Editorial Board: IEEE Control Systems Society	2016-2020
Scientific Committee Member: International Young Researcher Workshop Geometry, Mechanics, and Control Locations: Coimbra (Portugal), Padova (Italy), Paris (France), Madrid (Spain) Göttingen (Germany), KULeuven (Belgium)	2015-
Co-organizer (7th Biannual Meeting on System and Control Theory) Fields Institute for Research in Mathematical Sciences Workshop with A. Lewis, A.R. Mansouri, S. Yüksel (Queen's)	2016
Technical Program Committee: 55th Conference on Decision and Control, Las Vegas, USA	2016
Minisymposium co-organizer (Nonsmooth and variational techniques in control) SIAM Conference on Control and its Applications, Paris, France with R. Kipka (Queen's)	2015
Invited session organizer (Controllability of network control systems) Control and Decision Conference, Osaka, Japan with M-A. Belabbas (UIUC) and C. Aguilar (CSUB)	2015
Invited session organizer (Controllability of network control systems) Control and Decision Conference, Los Angeles with M-A. Belabbas (UIUC) and C. Aguilar (CSUB)	2014
Invited session organizer (Stabilization of network control systems) Control and Decision Conference, Los Angeles with M-A. Belabbas (UIUC) and C. Aguilar (CSUB)	2014
Minisymposium co-organizer (Adversarial networks: learning and information exploitation) SIAM Conference on Control and its Applications, Baltimore with J. Cortes (UCSD)	2011
Tutorials Chair: 27th Biennial Symposium on Communications Conference Kingston, Canada	2014
NSERC Discovery Grants Reviewer	2016-

$Reviewer\ for:$

Journal of Nonlinear Analysis, IEEE Transactions on Network Science and Engineering, IEEE Control Systems Letters, European Journal of Operational Research, Journal on Special Matrices, IEEE Transaction

on Signal Processing, Open Access Game Theory Journal, SIAM Journal on Control and Optimization, IEEE Transaction on Cybernetics: Systems, IEEE Transaction on Automatic Control, IEEE Transactions on Control of Network Systems, IEEE Transaction on Power Systems, IEEE Transactions on Energy Conversion, Automatica, European Journal of Control, Journal of Geometric Mechanics, Mathematics of Control, Signals, and Systems, IEEE Journal of Robotics and Automation, Journal of Systems, Control and Communication, ASME Journal of Dynamic Systems, Measurement and Control, Nonlinear Dynamics, Computational and Applied Mathematics, IEEE Transactions on Control Systems Technology, Control Systems Magazine, Annual Conference on Neural Information Processing Systems (NIPS), Games: Advances in Evolutionary Game Theory and Applications, IEEE Conference on Decision and Control, American Control Conference, IEEE/RSJ Conference on Intelligent Robots and Systems, IEEE Multi-conference on Systems and Control, International Federation of Automatic Control Conferences, Canadian Biennial Symposium on Communications, Journal of Dynamical and Control Systems, NeurIPS, ICML

Book Reviews:

Springer, CRC Press (Taylor and Francis Group), Annual Reviews in Control

INVITED TALKS AND SEMINARS

INVITED TALKS AND SEMINARS	
Invited talk, International Congress on Industrial and Applied Mathematics,	Tokyo August 2023
Invited speaker, Banff International Research Station, Banff	June 2023
Geometry, Topology and Control System Design	
Colloquium, University of California, San Diego	June 2023
Invited speaker, Information Theory and Applications Workshop, San Diego	February 2023
Seminar talk, University of Colorado, Boulder	December 2022
Seminar talk, University of Illinois, Urbana-Champaign	October 2022
Seminar talk, University of Bologna	September 2022
Seminar talk, École des Mines de Paris	May 2022
Applied Math Colloquium, University of California, Los Angeles	May 2022
Seminar talk, University of California, Riverside	April 2022
Seminar talk, University of California, Santa Barbara	January 2022
Seminar talk, Center for Artificial Intelligence, RWTH Aachen University	November 2021
Seminar talk, University of California Los Angeles	October 2021
Seminar talk, University of California Los Angeles	November 2021
IEEE-Eta Kappa Nu, Gamma Chapter	
Seminar talk, Technion	April 2021
Seminar talk, Grenoble	February 2021
Seminar talk, Technical University of Munich	January 2021
Seminar talk, Peking University	August 2020
Colloquium, University of Maryland	October 2020
Booz Allen Hamilton Distinguished Colloquium Lecture	
Seminar talk, University of Passau	July 2020
Seminar talk, ETH Zürich	January 2020
Colloquium, University of California Los Angeles	January 2020
Seminar talk, University of Stuttgart,	October 2019
Colloquium talk, University of Waterloo	September 2019
Colloquium talk, Queen's University	September 2019
Plenary talk, CAIMS Annual meeting, Whistler	June 2019
Canadian Society of Applied and Industrial Mathematics	
Seminar talk, University of California, San Diego	May 2018
Colloquium, University of Stuttgart	July 2017
Colloquium, University of Toronto	April 2017
Seminar talk, University of Salento, Lecce	June 2016
Colloquium, University of Stuttgart	June 2016

Colloquium, University of Colorado, Boulder	April 2016
Invited speaker, Allerton Conference Monticello, Illinois	October 2016
Communication, Control, and Computing	0 + 1 - 2015
Invited speaker, Allerton Conference Monticello, Illinois	October 2015
Communication, Control, and Computing	D
Seminar talk, Concordia University	December 2014
Invited talk, McMaster University	December 2014
The Canadian Mathematical Society Meeting,	October 2014
Invited speaker, Allerton Conference Monticello, Illinois Communication, Control, and Computing	October 2014
Invited speaker, Banff International Research Station	October 2014
Optimal Cooperation, Communication, and Learning in Decentralized Systems	
Invited speaker, University of Waterloo	May 2014
Sixth Biannual Meeting on Systems and Control Theory	v
Seminar talk, McGill University	November, 2013
Centre for Intelligent Machines	
Invited seminar, University of Washington St. Louis	April 2013
Invited seminar, Technical University of Munich	April 2013
Invited seminar, Queen's University	March 2013
Invited seminar, Harvard University	March 2013
Invited seminar, University of California Los Angeles	March 2013
Invited seminar, Groningen University	February 2013
Invited seminar, Georgia Institute of Technology	February 2013
Invited seminar, Utah State University	February 2013
INVITED RESEARCH VISITS/WORKSHOPS AND SYMPOSIUMS	
Southern California Applied Math Symposium, UC Irvine	April 2023
Information Theory and ApplicationsWorkshop, UC San Diego	Jan 2023
Southern California Control Workshop UC Irvine	April 2022
Research Visit RWTH Aachen University	November 2021
Learning for Dynamics and Control, MIT	May 2019
Princeton Day of Optimization, Princeton University	Sep 2018
Research Visit, Electrical and Computer Engineering, UC San Diego	June 2018
Visiting Faculty, Institute for Systems Theory and Automatic Control, University o	
Jean-Michel Coron's 60th birthday, Institute Henri Poincare, Paris, France	June 2016
Visiting Faculty, Institute for Systems Theory and Automatic Control, University o Research Visit, Department of Electrical, Computer, and Energy Engineering,	of Stuttgart July 2016
University of Colorado, Boulder	April 2016
Nonlinear Control and Geometry, Banach Centre, Poland	August 2015
Optimal Cooperation, Communication, and Learning in Decentralized Systems,	1148450 2010
Banff International Research Station	October 2014
Research Visit, Mechanical and Aerospace, UC San Diego, San Diego	June 2014
Symposium on Mathematical Theory of Networks and Systems, Groningen	July 2014
The 27th Biennial Symposium on Communications, Kingston	May 2014
Sixth Biennial Meeting on Systems and Control Theory, University of Waterloo	May 2014
The 2nd Midwest Workshop on Control and Game Theory, University of Notre Dan	
Workshop on Information and Decision in Social Networks, MIT	2012
The 1st Midwest Workshop on Control and Game Theory, UIUC	2012
Symposium on Emerging Topics in Control and Modelling, UIUC	2012
3rd IFAC Workshop on Distributed Estimation and Control in Networked Systems,	Santa Barbara 2012
Initiative for Mathematical Sciences and Engineering, UIUC	, 2012
Midwest Workshop on Control and Game Theory, UIUC	2012

Southern California Control Workshop, UC Los Angeles	2012
Southern California Control Workshop, UC Riverside	2011
Southern California Control Workshop, UC Santa Barbara	2010
Symposium on Mathematical Theory of Networks and Systems, Blacksburg	2006
A Celebration of Raoul Bott's Legacy in Mathematics, Montreal	2007

MEMBERSHIPS

- American Mathematic Society (AMS)
- Institute for Operations Research and the Management Sciences (INFORMS)
- The Canadian Applied and Industrial Mathematics Society (CAIMS)
- Society of Industrial and Applied Mathematics (SIAM)
- Institute of Electrical and Electronics Engineers (IEEE)
- IEEE Control Systems Society

TEACHING ACTIVITES

ECE242, Nonlinear Dynamics, UCLA	Winter 2023
ECE239AS, Decision Making in Stochastic Systems, UCLA	Fall 2022
ECE239AS, Control, Identification, and Learning Algorithms, UCLA	Spring 2022
ECE141, Principles of Feedback Control, UCLA	Winter 2022
MTHE 332, Introduction to Control Systems, Queen's	Winter 2019
MTHE 430, Control Systems, Queen's	Fall 2018
MTHE 332, Introduction to Control Systems, Queen's	Winter 2018
APSC 174, Linear Algebra, Queen's	Winter 2018
MATH 932, Calculus of Variations and Optimal Control, Queen's	Winter 2017
MTHE 332, Introduction to Control Systems, Queen's	Winter 2017
APSC 174, Linear Algebra, Queen's	Winter 2017
MTHE 434, Optimization Theory and Applications, Queen's	Fall 2016
APSC 200, Engineering Design Project, Queen's	Fall 2016
MTHE 332, Introduction to Control Systems, Queen's	Winter 2016
APSC 174, Linear Algebra, Queen's	Winter 2016
MTHE 434, Optimization Theory and Applications, Queen's	Fall 2015
APSC 200, Engineering Design Project, Queen's	Fall 2015
APSC 174, Linear Algebra, Queen's	Winter 2015
MTHE 430, Control Systems, Queen's	Fall 2014
APSC 200, Engineering Design Project, Queen's	Fall 2014
MTHE 335, Methods in Applied Mathematics (Distribution Theory), Queen's	Winter 2014
APSC 200, Engineering Design Project, Queen's	Fall 2013
MTHE 334, Methods in Applied Mathematics (Signals and Systems), Queen's	Fall 2013
ECE 580, Optimization by vector space methods, UIUC (Guest lecturer)	Fall 2012
MATH 235, Differential Equations, Queen's	Fall 2008
MATH 235, Differential Equations, Queen's	Fall 2007

SUPERVISORY ACTIVITIES

Current Group Members:

- ullet Postdoctoral Researchers:
- Graduate Students:

2022-1. Amirreza Neshaei Moghaddam, Ph.D., Topic: Convergence rate analysis in reinforcement learning 2. **Annika Fürnsinn**, Ph.D., 2019-Topic: Generalized Lyapunov functions and model predictive control Alumni: • Postdoctoral Researchers: 1. **Dr. Mohammad Akbari**, (online learning and control) 2022-2023 Current Placement: Machine learning consultant 2. Dr. Kexue Zhang, (delayed differential equations, event-triggered control systems) 2017-2019 Current Placement: Assistant Professor, Department of Mathematics and Statistics, Queen's University 3. Dr. Robert Kipka, (co-advised, infinite-dimensional optimal control), Current Placement: Associate Professor, Department of Mathematical Sciences, Lake Superior State University • Graduate Students: 1. Somya Singh, Ph.D. 2018-2023 Topic: Interacting Polya urns 2. Justin Veiner . M.Sc. 2021-2023 Topic: Generative adversarial networks based on a general parameterized family of loss functions 3. Daniel Adu Owusu, Ph.D. 2017-2022 Topic: Optimal transport in mechanism design, differential games and ensemble control Placement: Assistant Professor (limited term), Department of Mathematics, University of Georgia 4. Mohammad Akbari, Ph.D., 2017-2022 Topic: Online learning in control theory Placement: Postdoctoral scholar, Queen's University 2020-2022 5. Adam Gronowski, M.Sc. Topic: Information bottleneck methods for fairness and privacy in machine learning Awards: Vector Institute Scholarship Canadian Society of Information Theory Best Paper Award *Placement*: co-founder of capsa AI 6. **Xu Chen**, M.Sc, (with C. Ebenbauer at Stuttgart University), 2020-2021 Thesis: Stability analysis of the ADAM algorithm Placement: Ph.D. student, Aachen University 7. Himesh Bhatia, M.Sc. 2018-2020 Topic: Generative adversarial networks Awards: Dorrance Family Award 8. Greg Harrington, M.Sc. 2017-2020 Topic: Optimization policies for Polya contagion networks) Awards: Queen's Frank E Smith, Queen Elizabeth II Graduate Scholarship in Science and Technology *Placement*: Ciena 9. Michael McCreesh, M.Sc., 2017-2019

10. **Simon Michalowsky**, visiting Ph.D. student

Awards: NSERC, Queen's Tri Council, OGS

2015-2019

Institute for Systems Theory and Automatic Control (University of Stuttgart)

Placement: Ph.D. student, Mechanical and Aerospace Engineering, UC San Diego

Topic: Lie bracket approximation for distributed optimization

Topic: Accelerated convergence of saddle-point dynamics

11. Scott Kyle, M.Sc.

2017-2019

Topic: Control of nonholonomic mechanical systems using virtual surfaces

Placement: MacLean Engineering

12. Diego Cardenas, M.Sc.

2018-2019

Topic: On the Kalman filter with intermittent observations *Placement*: Ph.D. student, *University of Agder, Norway*

13. Connor Boyd, M.Sc.

2017-2018

Topic: Vakonomic and non-holonomic dynamics *Placement*: Machine Learning Developer, Blue-Cat

14. Alireza Samsamshariat, M.Sc.

2017-2018

Topic: Martingale optimal transportation

Placement: Data Scientist, Zynga

15. Mikhail Hayhoe, M.Sc.

2015-2017

Thesis: A Polya urn stochastic model for the analysis and control of epidemics on networks Awards: ACC Best Paper Award Finalist, Queen's F. E. Smith, NSERC Queen's Graduate Award

Placement: Ph.D. student, Electrical and Systems Engineering, University of Pennsylvania

16. Jeremy Coulson, M.Sc.

2015-2017

Thesis: Average controllability of random heat equations

Awards: NSERC, Queen's Tri Council, OGS, Queen's H. K. Walter

Placement: Ph.D. student, Automatic Control Laboratory, ETH Zurich

Assistant Professor, Electrical & Computer Engineering, University of Wisconsin-Madison

17. Drew Steeves, M.Sc.

2015-

Thesis: Controllability of underactuated coupled parabolic systems

Awards: Queen's Senator Frank Carrel, Queen's Graduate Award, Queen Elizabeth II Graduate Scholarship in Science and Technology

Placement: Ph.D. student, Mechanical and Aerospace Engineering, UC San Diego

AV Planning & Prediction, Nissan

18. Pouya Rezaeinia, M.Sc.

2015-2017

Thesis: Push-sum algorithm on time-varying random graphs Placement: Ph.D. student. Sauder Business School. UBC

Management Consultant at CPCS

19. Daniel Adu Owusu, M.Sc.,

2013-2014

Project: On ensemble control systems

Placement: Ph.D. student Mathematics, Queen's University Limited term Assistant Professor, Department of Mathematics, University of Georgia

20. Mohammad Akbari, M.Sc.

2013-2015

Thesis: Distributed online optimization on time-varying networks

Placement: Ph.D. student Mathematics, Queen's University

21. Babak Beheshti Vadeqan, M.Sc.

2014-2016

Thesis: Geometry of Dirac Operators,

Placement: Ph.D. student Mathematics, Western University

22. Ali Khanafer, Ph.D. (visiting student from UIUC),

2012-2014

Thesis: Information spread in networks: games, optimal control, and stabilization

Placement: IBM

• Undergraduate Research Students:

♦ 2019-2020:

- Rebecca Bonham Carter (NSERC USRA)
- Fernando Camacho (NSERC USRA)

 Project: Rough path theory

♦ 2018-2019:

- Ian Hogeboom-Burr (Summer Work Experience Program)
 Project: Experimental design of leader-follower robotics laboratory
- Bryony Schonewille (Summer Work Experience Program)
 Project: Experimental design of leader-follower robotics laboratory
- Hugh Corley (Summer Work Experience Program)
 Project: Experimental design of leader-follower robotics laboratory

♦ 2017-2018:

- Himesh Bhatia (NSERC USRA)
 Project: Passivity and self-appraisal dynamics
- Daniel Tamming (Summer Work Experience Program)
 Project: Experimental design of leader-follower robotics laboratory
- Fernando Camacho (Summer Work Experience Program)
 Project: Experimental design of leader-follower robotics laboratory

♦ 2016-2017:

- Rebecca Bonham-Carter (NSERC USRA)

 Project: Extensions of sparse stable matrix systems
- Michael McCreesh (NSERC USRA)
 Project: Metzler sparse stable matrix cones
- Himesh Bhatia (Summer Work Experience Program)
 - Project: Experimental design of leader-follower robotics laboratory
- Stephen Chisnall (Summer Work Experience Program)
 Project: Experimental design of leader-follower robotics laboratory

♦ 2015-2016:

Drew Steeves (Summer Work Study Program)
 Project: Re-design of the Modern Control Laboratory

♦ 2014-2015:

- Drew Steeves (Summer Work Experience Program)
 Project: Convergence rate of one-sided asymmetric Hegselmann-Krause dynamics
- Jeremy Coulson (Summer Work Experience Program)
 Project: Convergence rate of one-sided asymmetric Hegselmann-Krause dynamics

• Undergraduate Thesis Students:

♦ 2018-2019:

- Lachlan Devir, Chris Caromicoli, Andrew Downie, Alex Taylor (Keyser Prize for best project)
 Thesis: Motion planning in dynamic environments
- Luke Chau, Simon Kersten, Thomas Huckell, Benji Christie Thesis: Predictive control for an autonomous boat
- Coby Davis, Ted Bursey, Julian Gailiunas, Jason Benchetrit Thesis: Predictive control for transportation
- Adam Boljkovac, Steven Lee, Patrick Chin, Jordana Sherman Motion planning in dynamic environments

♦ 2016-2017:

- Cleo Savides, Joshua Dirocco, Mareena Macpherson (Keyser Prize for best project)
 Thesis: Underwater source seeking using a deformable fish
- Greg Harrington, Sarah Colquhoun, Kerem Ataman, Tristen Ognibene
 Thesis: Analysis and control of contagious phenomena in networks

♦ 2015-2016:

- Taylor Reynolds, True Wilson, Matthew Boyd (Keyser Prize for best project)
 Thesis: Extremum seeking control methods for nonholonomic source seeking vehicles
- Jacob Malleau, Soraya Weaver, Rehman Shivji, Aaron Short Thesis: Dynamic vehicle routing for UBER

♦ 2014-2015:

- Drew Steeves, Jeremy Coulson, Ted Donnelly, Thomas Hall (Keyser Prize for best project)
 Thesis: Synchronization of coupled oscillators: power networks
- Ryan Farrell, Mikhail Hayhoe, Justin Ma, Mark Mahony
 Thesis: Distributed triggering strategies for deployment of autonomous mobile networks with outdated information
- Matthew Slavin, Michael Mehta, Kendra MacKay, Eve Laverty (co-supervised)
 Thesis: Formation dynamics
- John Ramsey, Daniel Potvin, Brendon Conlin (co-supervised)
 Thesis: Extending a Polya contagion process to modelling contagion in networks with finite memory
- Hannah Koke, Brynn Vadala (co-supervised)
 Thesis: Profiling Contagious Behaviour in Networks

♦ 2013-2014:

- Marlee Vandewouw, Karin Martin (Keyser Prize for best project)
 Thesis: Distributed algorithms for deployment of autonomous mobile networks
- Ian Ross, Evangelian Collings, Taylor Adams
 Thesis: Formation dynamics of multi-agent systems

THESIS COMMITTEE/CANDIDACY EXAM MEMBER

- Mona Buisson Fenet, Ph.D., École des Mines de Paris, 2023
- Aaron John Sabu, M.Sc., UCLA, 2023
- Kangdi Yu, M.Sc., UCLA, 2023
- Jonathan Burton, Ph.D., UCLA, 2022
- Lucas Fraile, Ph.D., UCLA, 2022
- Derek Xioa, Ph.D., UCLA, 2022
- Muratkhan Abdirash, Ph.D., UCLA, 2022
- Zida Wu, Ph.D., *UCLA*, 2022
- Jan Feiling Ph.D., University of Stuttgart, 2021
- Ahmed Shaltut, M.Sc., Queen's University, 2021
- Xin Cheng, Ph.D., Queen's University, 2021
- Mohammad Yaali Jahromi, M.Sc., Queen's University, 2020
- Bora Yongacoglu, Ph.D., Queen's University, 2018
- Sina Sanjari, Ph.D., Queen's University, 2018
- Yanlei Zhang, P.hD., Queen's University, 2018-

- Graeme Baker, M.Sc., Queen's University, 2018
- Sina Sanjari, M.Sc., Queen's University, 2017
- Kiraseya Preusser, M.Sc., Queen's University, 2017
- Iman Askarian, M.Sc., Queen's University, 2016
- Tristan Mines, M.Sc., Queen's University, 2016
- Francois Seguin, Ph.D., Queen's University, 2016
- Judith Ebegbulem, M.Sc., (Chem-Eng), Queen's University, 2016
- Ryan Bennett, M.Sc. (Chem-Eng), Queen's University, 2015
- Khaled Hayajneh, Ph.D. (ECE), Queen's University, 2015
- Arghavan Modiri, M.Sc. (ECE), Queen's University, 2015
- Michael Cabral, M.Sc., Queen's University, 2014
- Hossein Mousavian, Ph.D., Queen's University, 2014
- Sousan Beigi Harchegani, M.Sc. (ECE), Queen's University, 2014
- Naci Saldi, Ph.D., Queen's University, 2013
- Saber Jafarpour, Ph.D., Queen's University, 2013
- Emmanuel Ogbe (Chem-Eng), Ph.D., Queen's University, 2013
- Joshua Pohlkamp-Hartt, Ph.D., Queen's University, 2016
- Youness Aliyari, Ph.D., Queen's University, 2013
- Melkior Ornik, M.Sc., Queen's University, 2013

PUBLICATIONS

PREPRINTS

- Marc Weber, Christian Ebenbauer, and Bahman Gharesifard Alternatives to Nussbaum control, working paper, 2022
- 2. Pouya Rezaienia and Bahman Gharesifard, Tamas Linder, Distributed optimization with uncertain communications, preprint available on arXiv, 2022
- 3. Bahman Gharesifard and Andrew D. Lewis, The trouble with imaginary eigenvalues. Optimal control, controllability, frequency response, preprint, March 2020
- 4. Bahman Gharesifard, and Xudong Chen, Characterization of structural averaged controllability of linear ensemble systems, in submission to **IEEE Transactions on Automatic Control**, draft available, 2023
- 5. Somya Singh, Fady Alajaji, and *Bahman Gharesifard* A preferential attachment model based on a Pólya urn with increasing colors, in submission to **Network Science**, Cambridge University Press, 2023

JOURNALS

- 1. Justin Veiner, Fady Alajaji, and *Bahman Gharesifard*, A unifying generator loss function for generative adversarial networks, **SIAM Journal on Mathematics of Data Science**, submitted, 2023
- 2. Alex Olshevsky and *Bahman Gharesifard*, A small-gain analysis of single timescale actor critic, **SIAM**Journal on Control and Optimization, to appear, 2023
- Mohammad Akbari, Bahman Gharesifard, and Tamas Linder, Logarithmic regret for adaptive control
 of linear quadratic regulators using hints, Journal of Machine Learning Research, submitted,
 2022
- 4. Annika Fürnsinn, Christian Ebenbauer, and Bahman Gharesifard, Relaxed feasibility and stability criteria for flexible-step model predictive control, IEEE Control Systems Letters, to appear, 2023
- 5. Matteo Marchi, Jonathan Bunton, *Bahman Gharesifard*, Paulo Tabuada, Point cloud registration with sharp performance bounds, **IEEE Control Systems Letters**, to appear, 2023
- 6. Annika Fürnsinn, Christian Ebenbauer, and *Bahman Gharesifard*, Flexible-step model predictive control based on generalized Lyapunov functions, **Automatica**, provisionally accepted, 2023
- 7. Behrouz Touri and Bahman Gharesifard, A united framework for continuous-time distributed optimization, SIAM Journal on Control and Optimization, to appear, 2023
- 8. Adam Gronowski, William Paul, Fady Alajaji, Bahman Gharesifard, and Philippe Burlina Classification Utility, Fairness, and Compactness via Tunable Information Bottleneck and Rényi Measures, IEEE Transactions on Information Forensics and Security, accepted with minor revision, 2023
- 9. Paulo Tabuada and Bahman Gharesifard, Universal approximation power of deep residual neural networks through the lens of control, IEEE Transactions on Automatic Control, to appear, 2023
- 10. Kexue Zhang and Bahman Gharesifard, and Elena Braverman, A note on the stability of event-triggered control systems with delay, IEEE Transactions on Automatic Control, submitted, 2022
- 11. Mohammad Akbari, *Bahman Gharesifard*, and Tamas Linder, Logarithmic regret in online linear quadratic control using Riccati updates, **Mathematics of Control, Signals, and Systems**, 2022
- 12. Karthik Elamvazhuti, Bahman Gharesifard, Andrea Bertozzi, and Stanley Osher, Neural ODE control for trajectory approximation of continuity equation, **IEEE Control Systems Letters**, 3152 3157 2022
- 13. Matteo Marchi, Johnathan Bunton, *Bahman Gharesifard*, and Paulo Tabuada, Stability guarantees for control loops with deep learning state estimation, **IEEE Control Systems Letters**, 6, 1286 1291, 2021
- 14. Daniel Adu, Tamer Başar, and *Bahman Gharesifard*, Optimal transport for a class of linear quadratic differential games, **IEEE Transactions on Automatic Control**, 67(11), 6287 6294, 2022
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