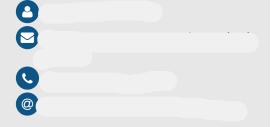
Riccardo Spezialetti

3D Computer Vision Scientist

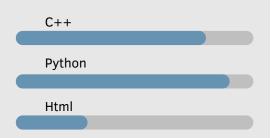


About Me

I am Computer Vision Scientist who, for the last 5 years, focused his studies on shape processing, geometry and deep learning.

I enjoy looking for simple and intuitive solutions to complex problems. If you don't see me sitting at my desk, you'll find me running out in the park or behind my reflex taking pictures.

Coding languages -



Languages



Working Experience

currently **Research Scientist at Eyecan**

I'm currently enrolled as a research scientist at Eyecan, a spinoff from the University of Bologna founded in 2020. The main goal of our company is to generate annotated data for AI purposes using robots and, thus, without the need for Human Annotations.

Postdoctoral Researcher at COMPUTER 2020-2022 **VISION LAB**

University of Bologna

evecan.ai

I worked as a postdoctoral research fellow at the Computer Vision Lab of the university of Bologna under the supervision of Professor Luigi Di Stefano and Professor Samuele Salti. My research topics focused on Deep Learning solutions for 3D Computer Vision problems such as 3D shape generation from images, surface registration and implicit functions.

2020-2022 **Tutor Machine Learning for Computer Vision** University of Bologna I worked as a teaching tutor for the course held by professor Prof.

Samuele Salti.

2020-2022 **Tutor Computer Vision and Image Processing** University of Bologna I worked as a teaching tutor for the course held by professor Prof.

Luigi Di Stefano.

Visiting Researcher Scientist at Google contracted by 2019-2020 Randstad Randstad

I worked as a Visiting Researcher at Google Zurich contracted by Ranstad.

Ph.D. Student in Comptuer Science and 2016 - 2019 University of Bologna **Engineering**

I was a Ph.D. student at the Computer Vision Laboratory of the University of Bologna, under the supervision of Prof. Luigi Di Stefano. In my Ph.D thesis I propose a end-to-end features learning pipeline, based on deep learning techniques, to address Surface Matching on point cloud data.

2015 – 2016 C++ Developer

Datalogic

I worked in the 3D Computer Vision R&D division under the supervision of Federico Tombari and Marco Bottazzi.

The areas of interest were keypoint extraction on low cost sensor data, non-rigid registration of objects, and digitization of the human body.

Education

Study

2016 – 2019 Ph. D. in COMPUTER SCIENCE AND

ENGINEERING

Thesis: Learning to understand the world in 3D.

Supervisor: Luigi Di Stefano.

2012 – 2015 Master Degree In Computer Engineering

Final Rank: 110/110 with honors.

Master Thesis: Keypoints detection in 3D Point Cloud with Machine

University of Bologna

University of Bologna

Learning approach.

Supervisor: Luigi Di Stefano.

Co-supervisors: Samuele Salti and Federico Tombari.

2007 – 2011 Bachelor Degree In Computer Engineering University of Bologna

Final Rank: 91/110 with honors.

Master Thesis: Designing cloud services in Open Stack.

Supervisor: Antonio Corradi. **Co-supervisor**: Luca Foschini.

Publications

2023	ReLight My NeRF: A Dataset for Novel View Synthesis and Relighting of Real World Objects
	Toschi M., De Matteo R., Spezialetti R. , De Gregorio D., Di Stefano L., Salti S.
	Conference on Computer Vision and Pattern Recognition (CVPR)
2022	Self-Distillation for Unsupervised 3D Domain Adaptation <i>De Luigi L., Cardace A.,</i> Spezialetti R. , <i>Ramirez P. Z., Salti S., Di Stefano L.</i>
	International Conference on Learning Representations (ICLR)
2022	Self-Distillation for Unsupervised 3D Domain Adaptation <i>Cardace A., Spezialetti R., Ramirez P. Z., Salti S., Di Stefano L.</i> Winter Conference Of Computer Vision (WACV)
2021	Unsupervised Learning of Local Equivariant Descriptors for Point Clouds
	Marcon M., Spezialetti R. , Salti S., Silva L., Di Stefano L. IEEE Transactions on Pattern Analysis and Machine Intelligence (TPAMI)
2021	RefRec: Pseudo-labels Refinement via Shape Reconstruction for Unsupervised 3D Domain Adaptation
	Cardace A., Spezialetti R. , Ramirez P. Z., Salti S., Di Stefano L. In International Conference on 3D Vision (3DV)
2021	Go with the Flows: Mixtures of Normalizing Flows for Point Cloud Generation and Reconstruction
	Postels J., Liu M., Spezialetti R. , Van Gool L., Tombari, F. In International Conference on 3D Vision (3DV)
2020	A Divide et Impera Approach for 3D Shape Reconstruction from Multiple Views
	Spezialetti R., Tan D. J., Tonioni A., Tateno K., Tombari F. In International Conference on 3D Vision (3DV)
2020	Learning to Orient Surfaces by Self-supervised Spherical CNNs Spezialetti R., Stella F., Marcon M., Silva L., Salti S., Di Stefano L. Advances in Neural Information Processing Systems (NeurIPS)
2020	3D Local descriptors—from handcrafted to learned Spezialetti R., Salti S., Di Stefano L., Tombari F. 3D Imaging, Analysis and Applications
2020	Learning to understand the world in 3D R. Spezialetti
	Ph.D. Thesis
2019	Learning an Effective Equivariant 3D Descriptor Without Supervision
	Spezialetti R., Salti S., Di Stefano L.
2010	International Conference on Computer Vision (ICCV)
2019	GFrames: Gradient-Based Local Reference Frame for 3D Shape Matching
	Melzi S., Spezialetti R. , Tombari F., Bronstein M. M., Di Stefano L., Rodolá E.
	Conference on Computer Vision and Pattern Recognition (CVPR)
2019	Performance Evaluation of Learned 3D Features Spezialetti R., Salti S., Di Stefano L. International Conference on Image Analysis and Processing (ICIAP)
2018	Learning to Detect Good 3D Keypoints
-	Tonioni A., Salti S., Tombari F., Spezialetti R. , Di Stefano L.
2015	International Journal of Computer Vision (IJCV)
2015	Learning a descriptor-specific 3D keypoint detector Salti S., Tombari F., Spezialetti R. , Di Stefano L. International Conference on Computer Vision (ICCV)